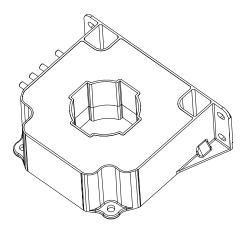


Current transducer LF 2010-S/SP28

 $I_{\rm P\,N}$ = 2000 A

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





Features

- · Bipolar and insulated current measurement up to 3.5 kA
- Current output
- · Closed loop (compensated) current transducer
- Panel mounting.

Special features

- $I_{PM} = 0 \dots \pm 3500 \,\text{A}$
- $\bullet \ \ U_{\rm d} \ = \ 12 \ \rm kV$
- Shield between primary and secondary
- Connection to secondary on M5 threaded studs.

Advantages

- · High accuracy
- Very low offset drift over temperature.

Applications

- Single or three phase inverters
- · Propulsion and braking choppers
- Propulsion converters
- High power drives
- Substations.

Standards

• EN 50155: 2021

• EN 50124-1: 2017

• EN 50121-3-2: 2016

• UL 508: 2010.

Application Domain

• Railway (fixed installations and onboard).





Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (−40 85 °C)	$\pm U_{\rm C\; max}$	V	±25.2
Primary conductor temperature	T_{B}	°C	100
Maximum steady state primary current (−40 85 °C)	I _{P N max}	Α	2000

Stresses above these ratings may cause permanent damage.

Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13

Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 600 V AC/DC, consideration shall be given to the following:

- 1 These products must be mounted in a suitable end-use enclosure.
- 2 The secondary pin terminals have not been evaluated for field wiring.
- 3 Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).
- 4 Based on the temperature test performed on all Series, the primary bar or conductor shall not exceed 100 °C in the end use application.

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.





Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_{\mathtt{d}}$	kV	12	Between primary and secondary + shield
			1	Between shield and secondary
Impulse withstand voltage 1.2/50 μs	U_{Ni}	kV	23.2	
Partial discharge RMS test voltage ($q_{\rm m}$ < 10 pC)	U_{t}	kV	4.8	Test carried out with a non insulated bar, diameter 40 mm, centered in the through-hole
Insulation resistance	R_{INS}	МΩ	200	measured at 500 V DC
Application example Rated insulation voltage RMS voltage	$U_{ m Nm}$	V	3700	Reinforced insulation according to IEC 62497-1, CAT III, PD2
Application example Rated insulation voltage RMS voltage	$U_{ m Nm}$	V	8000	Basic insulation according to IEC 62497-1, CAT III, PD2
Clearance (pri sec.)	d_{CI}	mm	53.7	Shortest distance through air
Creepage distance (pri sec.)	d_{Cp}	mm	53.8	Shortest path along device body
Comparative tracking index	CTI		600	
Case material	-	-	V0	According to UL 94

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	T_{A}	°C	-40		85	
Ambient storage temperature	T_{Ast}	°C	-50		90	
Equipment operating temperature class						EN 50155: OT6
Switch-on extended operating temperature class						EN 50155: ST0
Rapid temperature variation class						EN 50155: H2
Conformal coating type						EN 50155: NA
Mass	m	g		1500		

RAMS data

Parameter	Symbol	Unit	Min	Тур	Max
Useful life class					EN 50155: L4
Mean failure rate	Σ	h ⁻¹		1/2961551.6	According to IEC 62380: 2004 $T_{\rm A}$ = 45 °C ON: 20 hrs/day ON/OFF: 320 cycles/year $U_{\rm C}$ = ±24 V, $I_{\rm P}$ = 2000 A DC





Electrical data

At $T_{\rm A}$ = 25 °C, $\pm U_{\rm C}$ = ± 24 V, $R_{\rm M}$ = 1 Ω , unless otherwise noted. Lines with a * in the conditions column apply over the $-40 \dots 85$ °C ambient temperature range.

Parameter	Symbol	Unit	Min	Тур	Max		Conditions
Primary nominal RMS current	I_{PN}	Α			2000	*	
Primary current, measuring range	I_{PM}	Α	-3500		3500	*	
Measuring resistance	R_{M}	Ω	0			*	Max value of $R_{\rm M}$ is given in figure 1
Secondary nominal RMS current	I_{SN}	Α			0.4	*	
Resistance of secondary winding	$R_{\rm S}$	Ω			18.6		$R_{\rm S}(T_{\rm A}) = R_{\rm S} \times (1 + 0.004 \times (T_{\rm A} + \Delta {\rm temp-25}))$ Estimated temperature increase @ $I_{\rm PN}$ is $\Delta {\rm temp} = 15~{\rm ^{\circ}C}$
Secondary current	$I_{\mathtt{S}}$	Α	-0.7		0.7	*	
Number of secondary turns	N_{S}			5000			
Nominal sensitivity	S_{N}	mA/A		0.2			
Supply voltage	$\pm U_{\mathrm{C}}$	V	±14.25		±25.2	*	
Current consumption	$I_{\rm C}$	mA		42 + I _S 48 + I _S			$\pm U_{\rm C} = \pm 15 \text{ V}$ $\pm U_{\rm C} = \pm 24 \text{ V}$
Inrush current							NA (EN 50155)
Interruptions on power supply voltage class							NA (EN 50155)
Supply change-over class							NA (EN 50155)
Offset current, referred to primary	I_{O}	Α	-1		1		
Temperature variation of $I_{\rm O}$, referred to primary	I_{OT}	А	-1		1	*	
Magnetic offset current, referred to primary	I_{OM}	А		±1			After 3 × I _{PN}
Sensitivity error	$\varepsilon_{_{S}}$	%	-0.15		0.15	*	
Linearity error	$arepsilon_{L}$	% of I_{PN}	-0.1		0.1	*	
Total error	$arepsilon_{ ext{tot}}$	% of $I_{\rm PN}$	-0.2 -0.3		0.2 0.3	*	25 70 85 °C -40 85 °C
RMS noise current referred to primary	I_{no}	mA		90			1 Hz to 20 kHz (see figure 4)
Delay time to 10 % of the final output value $I_{\rm PN}$ step	t _{D 10}	μs		< 0.5			0 to 1 kA, 200 A/µs
Delay time to 90 % of the final output value $I_{\rm PN}$ step	t _{D 90}	μs		< 0.5			0 to 1 kA, 200 A/µs
Frequency bandwidth	BW	kHz		150			−3 dB, small signal bandwidth

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.



Typical performance characteristics

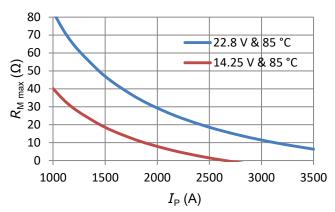


Figure 1: Maximum measuring resistance

$$R_{\mathrm{M \, max}} = N_{\mathrm{S}} \times \frac{U_{\mathrm{C \, min}} - 1.3 \, \mathrm{V}}{I_{\mathrm{P}}} - R_{\mathrm{S \, max}} \, \Omega$$

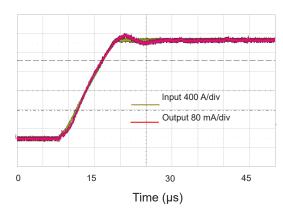


Figure 2: Typical step response (0 to 2 kA, 200 A/µs)

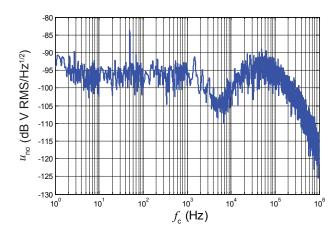


Figure 3: Typical noise voltage density $u_{\rm no}$ with $R_{\rm M}$ = 100 Ω

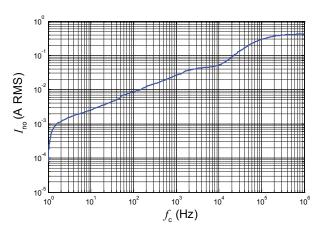


Figure 4: Typical total output current noise with $R_{\rm M}$ = 100 Ω (primary referred, RMS)

To calculate the noise in a frequency band $f_{\rm 1}$ to $f_{\rm 2}$, the formula is:

$$I_{\text{no}}(f_1 \dots f_2) = \sqrt{I_{\text{no}}(f_2)^2 - I_{\text{no}}(f_1)^2}$$

with $I_{no}(f)$ read from figure 4 (typical, RMS value).

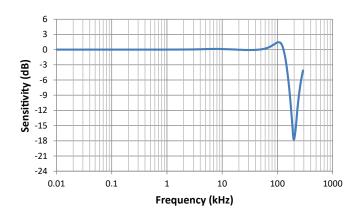
Example:

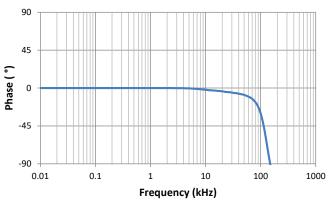
What is the noise from 1 to 10^6 Hz? Figure 4 gives $I_{\rm no}$ (1 Hz) = 0.2 mA and $I_{\rm no}$ (10 6 Hz) = 400 mA. The output current noise (RMS) is therefore:

$$\sqrt{(400 \times 10^{-3})^2 - (0.2 \times 10^{-3})^2}$$
 = 400 mA referred to primary



Typical performance characteristics





Figures 5 and 6: Typical frequency response, small signal bandwidth

Performance parameters definition

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to $I_{\rm PM}$, then to $-I_{\rm PM}$ and back to 0 (equally spaced $I_{\rm PM}/10$ steps).

The sensitivity S is defined as the slope of the linear regression line for a cycle between $\pm I_{\rm PM}$.

The linearity error $\varepsilon_{\rm L}$ is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Magnetic offset

The magnetic offset $I_{\rm O~M}$ is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

Electrical offset

The electrical offset current $I_{\rm O\;E}$ is the residual output current when the input current is zero.

Total error

The total error $\varepsilon_{\rm tot}$ is the error at $\pm I_{\rm P\,N}$, relative to the rated value $I_{\rm P\,N}$.

It includes all errors mentioned above.

Delay times

The delay time $t_{\rm D\,10}$ @ 10 % and the delay time $t_{\rm D\,90}$ @ 90 % with respect to the primary are shown in the next figure.

Both slightly depend on the primary current $\mathrm{d}i/\mathrm{d}t$. They are measured at nominal current.

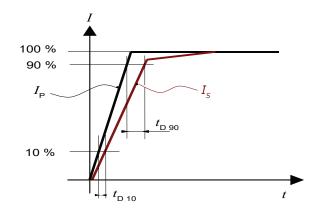
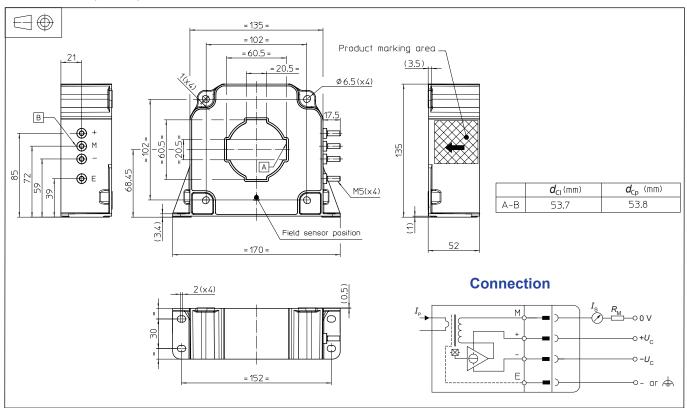


Figure 7: $t_{D,10}$ (delay time @ 10 %) and $t_{D,90}$ (delay time @ 90 %)



Dimensions (in mm)



Mechanical characteristics

General tolerance

Transducer fastening

Vertical position

Recommended fastening torque

Primary through-hole

Transducer fastening

Horizontal position

Recommended fastening torque

Connection of secondary

Recommended fastening torque

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary connection, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used. Main supply must be able to be disconnected.

Note: Additional information avaible on request.

Remarks

- I_s is positive when I_p flows in the direction of arrow.
- The secondary cables also have to be routed together all

±0.5 mm

Ø 57 mm

4 slotted holes Ø6.5 mm

4 slotted holes Ø 6.5 mm

on M5 threaded studs

4 M6 steel screws

5.5 N·m (±10 %)

2.2 N·m (±10 %)

4 M6 steel screws

5.5 N·m (±10 %)

60 mm × 20 mm

- Installation of the transducer is to be done without primary current or secondary voltage present.
- Maximum temperature of primary conductor: see page 2.
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: https://www.lem.com/en/file/3137/download.